

Certified Symmetry and Dominance Breaking for Combinatorial Optimisation

Bart Bogaerts, **Stephan Gocht**, Ciaran McCreesh, Jakob Nordström

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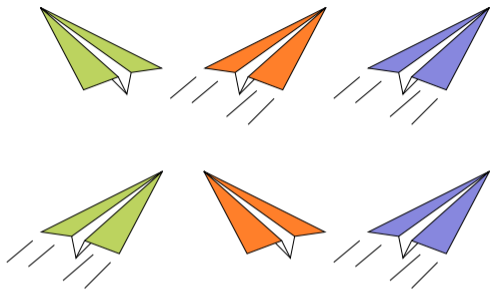
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- ▶ airline scheduling: have 3 aircraft
goal: assign which aircraft fly
- ▶ only need 2 (due to corona)
- ▶ aircraft are interchangeable
(encoding will be symmetric)



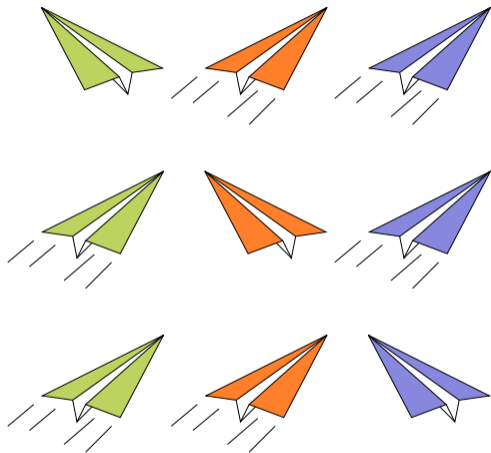
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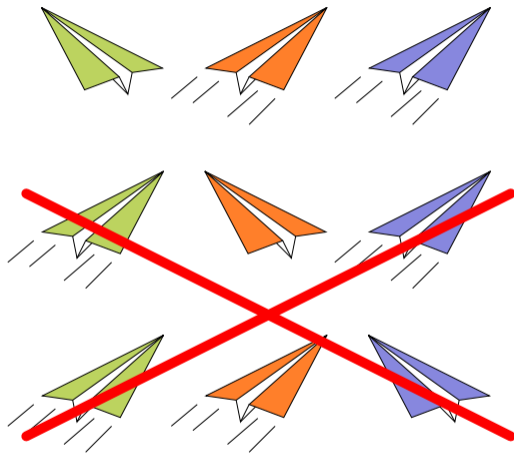
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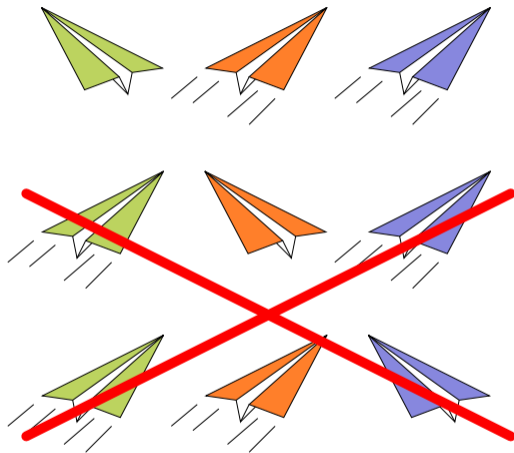
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by removing symmetric assignments



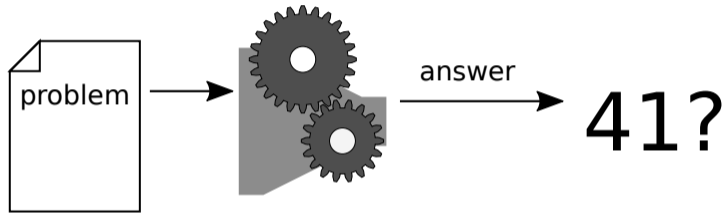
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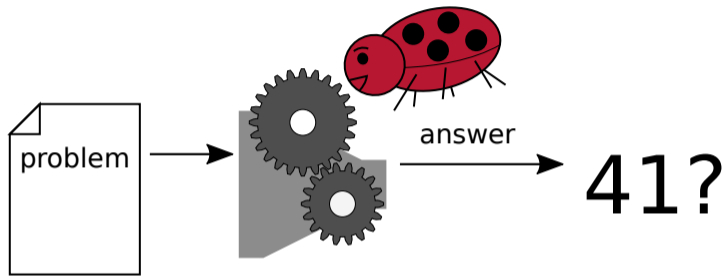


How can we know we didn't remove too many assignments?

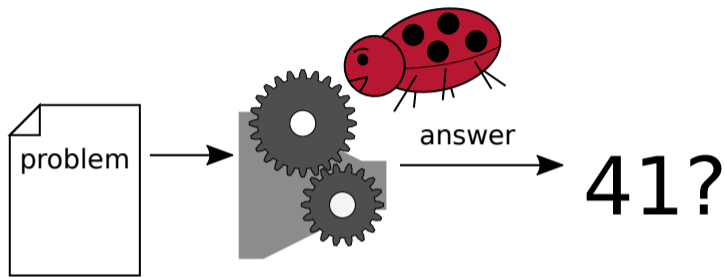
Detecting Bugs with Certifying Algorithms



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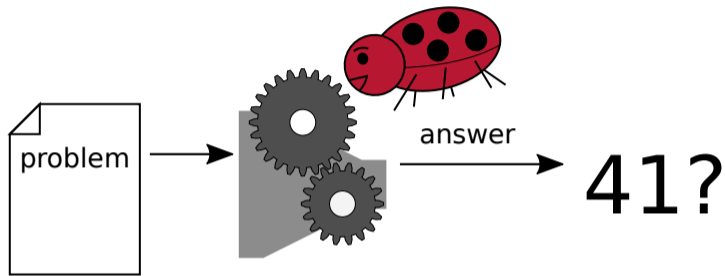


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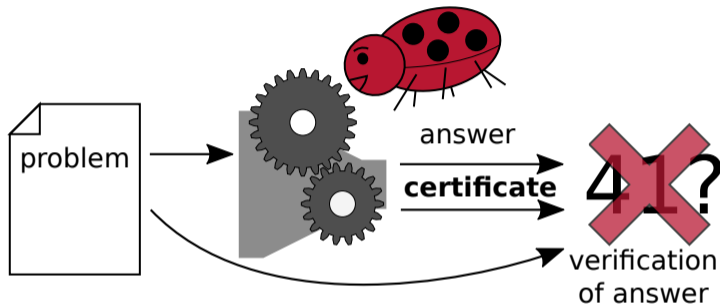
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Why Certifying Algorithms?

- ▶ during development
 - ▶ simplifies testing: no ground truth needed
 - ▶ find bugs even if result is correct
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 - ▶ increase trust in solution
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- ▶ while solving
 - ▶ increase trust in solution
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- ▶ after solving
 - ▶ analyse certificate to understand and improve solving process
 - ▶ could use certificate to audit solution afterwards

Requirements for Certifying Algorithms

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 - ▶ easy to implement in any solver
 - ▶ small performance overhead

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But how?

SAT Solving — A Success Story for Certifying Algorithms ...

- ▶ SAT = satisfiability of propositional formulas in conjunctive normal form (CNF)
- ▶ SAT competition requires solver to produce certificate (aka **proof logging**)

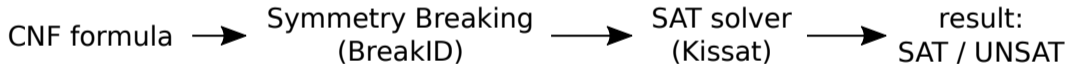
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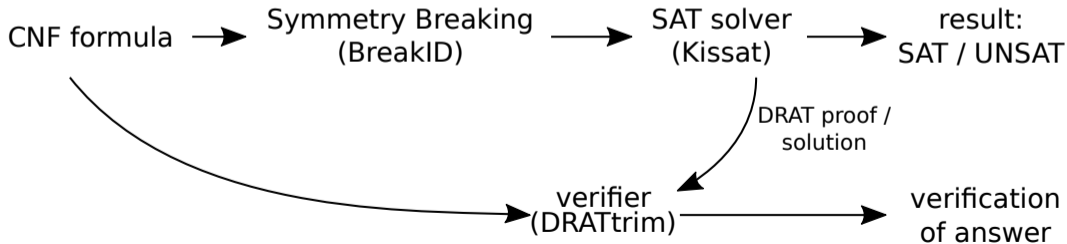
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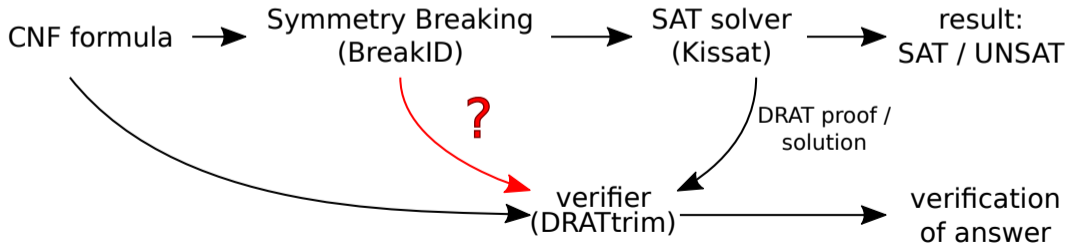
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... But Need for Further Research

- ▶ proof logging for symmetry breaking
 - ▶ no implementation available
 - ▶ approach based on DRAT proposed [HHW15]
 - ▶ not workable in practice
 - ▶ in particular, large or overlapping symmetries are problematic

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- ▶ How about practical proof logging for other solving paradigms?
 - ▶ MaxSAT solving
 - ▶ constraint programming (CP)
 - ▶ mixed integer programming (MIP)
 - ▶ algebraic reasoning / Gröbner basis computations
 - ▶ pseudo-Boolean satisfiability and optimization

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Need to look beyond DRAT!

New Proof Systems on the Rise

many new proof systems with implemented proof checkers:

- ▶ delete symmetry reverse unit propagation (DSRUP) [TD20]
- ▶ propagation redundancy (PR) [HKB17]
- ▶ practical polynomial calculus (PAC) [RBK18, KFB20]
- ▶ propagation redundancy for BDDs [BB21]
- ▶ Max-SAT resolution [PCH21]

Our Approach

- ▶ **general-purpose** proof format: pseudo-Boolean proofs (PBP)
- ▶ reference implementation of verifier: VeriPB¹
- ▶ allows easy proof logging for
 - ▶ reasoning with 0-1 linear inequalities (by design)
 - ▶ all-different constraints [EGMN20]
 - ▶ subgraph isomorphism [GMN20]
 - ▶ clique and maximum common (connected) subgraph [GMM⁺20]
 - ▶ parity/ XOR reasoning [GN21]

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This Work

- ▶ proof logging for symmetry and dominance breaking
- ▶ applied to SAT, constraint programming and max clique solving
- ▶ full support for optimization

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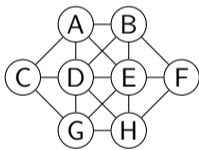
Supported Applications – Symmetry Breaking

- ▶ SAT

challenge: translate breaking constraint from PB to CNF

- ▶ Constraint Programming

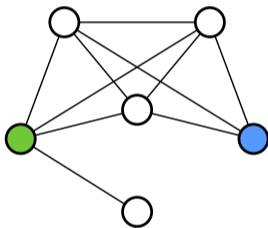
challenge: integer domains instead of 0-1



example: The Crystal Maze puzzle. Place numbers 1 to 8 without repetition, so that adjacent circles do not have consecutive numbers.

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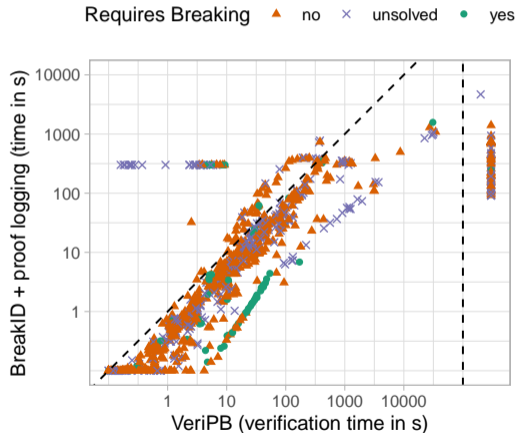
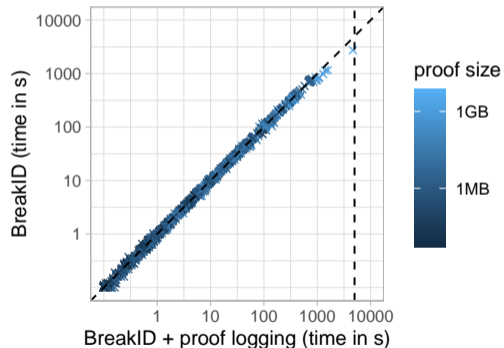
- ▶ maximum clique solving (find largest fully connected component)
challenge: lazy breaking



example: consider green but not blue node (every neighbour of blue is also neighbour of green)

Experiments

- ▶ evaluated on SAT competition benchmarks
- ▶ used BreakID² to find and break symmetries



²<https://bitbucket.org/krr/breakid/>

Running Example

$$\begin{array}{ll} \min: & 4x_1 + 2x_2 + x_3 \\ \text{s.t.} & x_1 + x_2 + x_3 \geq 2 \end{array}$$

- ▶ **boolean variable** x is 0 (false) or 1 (true)
(e.g. $x_1 = 1$ means green aircraft flies)
- ▶ **pseudo-Boolean constraint**:
linear inequality over variables
- ▶ **formula** F : set of constraints
- ▶ **objective function** f to be minimized

Goal: find assignment minimizing objective and satisfying all constraints

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$$\begin{array}{ll} \min: & 4x_1 + 2x_2 + x_3 \\ \text{s.t.} & x_1 + x_2 + x_3 \geq 2 \end{array}$$

Claim:

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$$3x_1 - 2x_2 - x_3 \leq 0$$

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How can we know this claim is correct?

Naive Attempt: Proof by Truth Table

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$$\text{s.t. } x_1 + x_2 + x_3 \geq 2 \quad (2)$$

Claim:

▶ without loss of generality, add

$$3x_1 - 2x_2 - x_3 \leq 0 \quad (3)$$

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objective value	x_1	x_2	x_3
0	0	0	0
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Not practical, need something more efficient!

Output from Symmetry Breaking

- ▶ give formula $x_1 + x_2 + x_3 \geq 2$ to symmetry breaker

objective value	x_1	x_2	x_3
0	0	0	0
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Output from Symmetry Breaking

- ▶ give formula $x_1 + x_2 + x_3 \geq 2$ to symmetry breaker
- ▶ output:
 - ▶ for permutation
 $\pi = \{ x_1 \mapsto x_2, x_2 \mapsto x_3, x_3 \mapsto x_1 \}$

objective value	x_1	x_2	x_3	
0	0	0	0	
1	0	0	1	} π
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 $(x_1 + x_2 + x_3 \geq 2)_{\upharpoonright\pi} = x_2 + x_3 + x_1 \geq 2$

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Notation: $C_{\upharpoonright\pi}$ substitutes variables in C as specified by π

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 - ▶ (syntactic) symmetry detected (ignoring objective)
 $(x_1 + x_2 + x_3 \geq 2)_{\uparrow\pi} = x_2 + x_3 + x_1 \geq 2$
 - ▶ breaking constraint
 $3x_1 - 2x_2 - x_3 \leq 0$ (falsified by purple assignments)

objective value	x_1	x_2	x_3	
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1	0	0	1	} π
2	0	1	0	
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The Dominance Rule

- ▶ idea (from dominance breaking):
 - ▶ allow to add constraint C , e.g, $3x_1 - 2x_2 - x_3 \leq 0$
 - ▶ if for every ρ falsifying C but satisfying F (purple)
 - ▶ we find ρ' that satisfies F and $f(\rho) > f(\rho')$

objective			
value	x_1	x_2	x_3
0	0	0	0
1	0	0	1
2	0	1	0
4	1	0	0
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Dominance Rule (simplified)

Can derive constraint C from formula F if a *witnessing* substitution ω is provided such that

$$F \cup \{\neg C\} \models F_{\upharpoonright\omega} \cup \{f > f_{\upharpoonright\omega}\}$$

objective value	x_1	x_2	x_3
0	0	0	0
1	0	0	1
2	0	1	0
4	1	0	0
3	0	1	1
5	1	0	1
6	1	1	0
7	1	1	1

Notation: $F \models F'$: satisfying assignment to F is also satisfying assignment to F'

The Dominance Rule — Example

- ▶ want to add $C: 3x_1 - 2x_2 - x_3 \leq 0$
- ▶ choose $\omega = \pi = \{x_1 \mapsto x_2, x_2 \mapsto x_3, x_3 \mapsto x_1\}$
- ▶ to prove: $F \cup \{\neg C\} \models F_{|\omega} \cup \{f > f_{|\omega}\}$, i.e.,

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Handwritten annotations: A right curly bracket on the right side of the table groups rows 5 and 6, with the symbol ω written next to it. Another right curly bracket is placed below the first one, also with the symbol ω next to it.

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- ▶ given $F: x_1 + x_2 + x_3 \geq 2$
and $\neg C: 3x_1 - 2x_2 - x_3 > 0$

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- ▶ given $F: x_1 + x_2 + x_3 \geq 2$
and $\neg C: 3x_1 - 2x_2 - x_3 > 0$
- ▶ derive $(x_1 + x_2 + x_3 \geq 2)|_{\omega}$
 $\equiv x_2 + x_3 + x_1 \geq 2$

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The Dominance Rule — Example

- ▶ want to add $C: 3x_1 - 2x_2 - x_3 \leq 0$
- ▶ choose $\omega = \pi = \{x_1 \mapsto x_2, x_2 \mapsto x_3, x_3 \mapsto x_1\}$
- ▶ to prove: $F \cup \{\neg C\} \models F|_{\omega} \cup \{f > f|_{\omega}\}$, i.e.,
- ▶ given $F: x_1 + x_2 + x_3 \geq 2$
and $\neg C: 3x_1 - 2x_2 - x_3 > 0$
- ▶ derive $(x_1 + x_2 + x_3 \geq 2)|_{\omega}$
 $\equiv x_2 + x_3 + x_1 \geq 2$
- ▶ and $4x_1 + 2x_2 + x_3 > (4x_1 + 2x_2 + x_3)|_{\omega}$
 $\equiv 4x_1 + 2x_2 + x_3 > 4x_2 + 2x_3 + x_1$
 $\equiv 3x_1 - 2x_2 - x_3 > 0$

objective value	x_1	x_2	x_3
0	0	0	0
1	0	0	1
2	0	1	0
4	1	0	0
3	0	1	1
5	1	0	1
6	1	1	0
7	1	1	1

Handwritten annotations: A red shaded region covers rows 0-4. A purple shaded region covers rows 5-6. A bracket on the right side of rows 3-5 is labeled ω . A bracket on the right side of rows 5-6 is labeled ω .

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The Dominance Rule — Further Remarks

Dominance Rule (simplified)

Can derive constraint C from formula F if a *witnessing* substitution ω is provided such that

$$F \cup \{\neg C\} \models F|_{\omega} \cup \{f > f|_{\omega}\}$$

objective

value	x_1	x_2	x_3
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1	0	0	1
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ω
 ω

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- ▶ “ \models ” replaced by **efficiently machine-verifiable** proof system (cutting planes)

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$\uparrow \omega$
 $\uparrow \omega$

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Dominance Rule (simplified)

Can derive constraint C from formula F if a *witnessing* substitution ω is provided such that

$$F \cup \{\neg C\} \models F_{\upharpoonright\omega} \cup \{f > f_{\upharpoonright\omega}\}$$

- ▶ “ \models ” replaced by **efficiently machine-verifiable** proof system (cutting planes)
- ▶ in paper: any strict order instead of $f > f_{\upharpoonright\omega}$

objective

value	x_1	x_2	x_3
0	0	0	0
1	0	0	1
2	0	1	0
4	1	0	0
3	0	1	1
5	1	0	1
6	1	1	0
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$\uparrow \omega$
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our work: proof logging for symmetry breaking (BreakID³) + verification (VeriPB⁴)

- ▶ simple to implement + efficient proof checking
- ▶ fully evaluated for symmetry breaking on SAT competition benchmarks
- ▶ proof of concept for
 - ▶ symmetry breaking in constraint programming
 - ▶ dynamic dominance breaking for maximum clique

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future work:

- ▶ proof logging for more techniques (e.g., in MaxSAT, CP or MIP)
- ▶ formally verified verifier

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